

Nonadherence in Dynamic Treatment Regimes – Moving Beyond Intention to Treat Analyses

Dylan Spicker

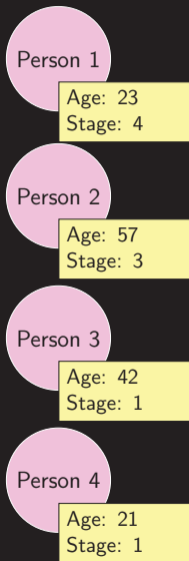
Department of Epidemiology, Biostatistics and Occupational Health
McGill University

Wednesday October 19, 2022

Precision Medicine

Treat the patient, not the disease.

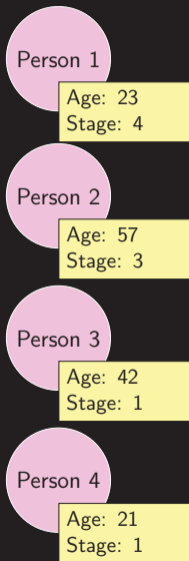
Dynamic Treatment Regimes



Experimental Treatment
($A = 1$)

Standard Treatment
($A = 0$)

Dynamic Treatment Regimes



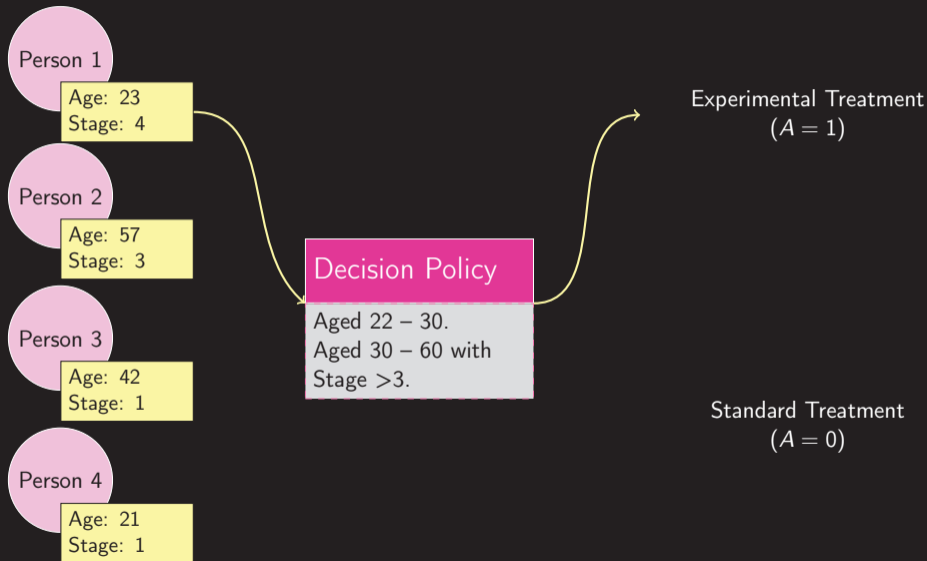
Decision Policy

Aged 22 – 30.
Aged 30 – 60 with
Stage >3.

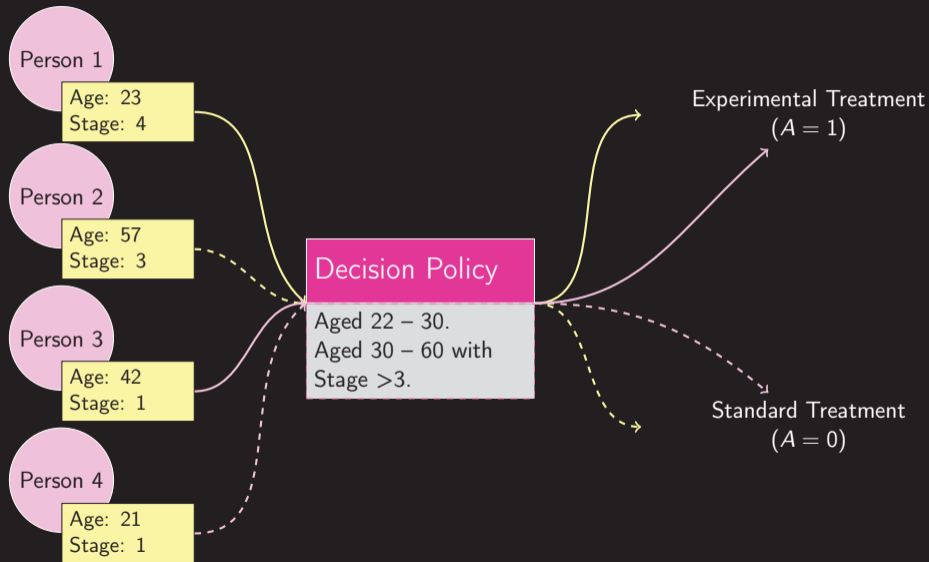
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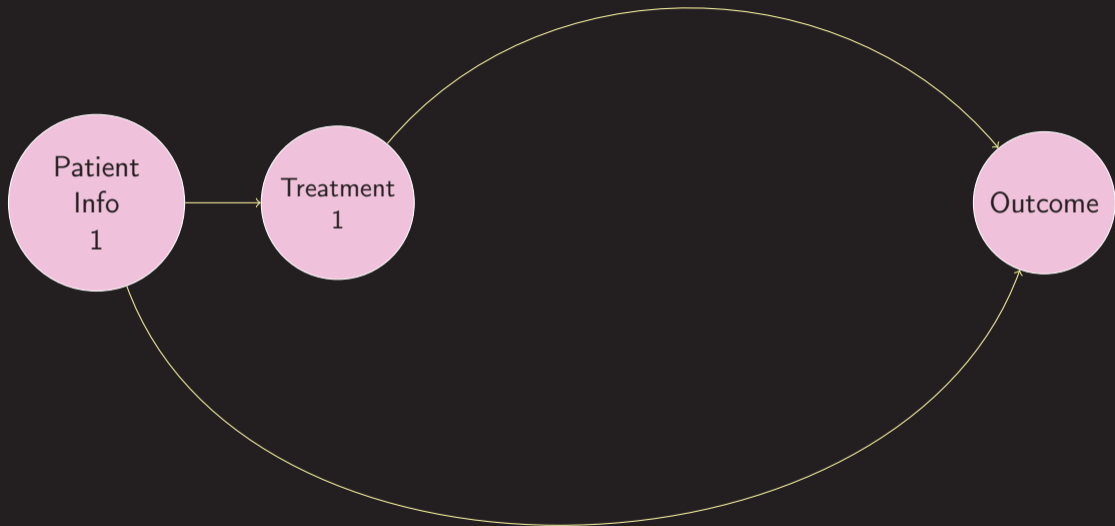
Standard Treatment
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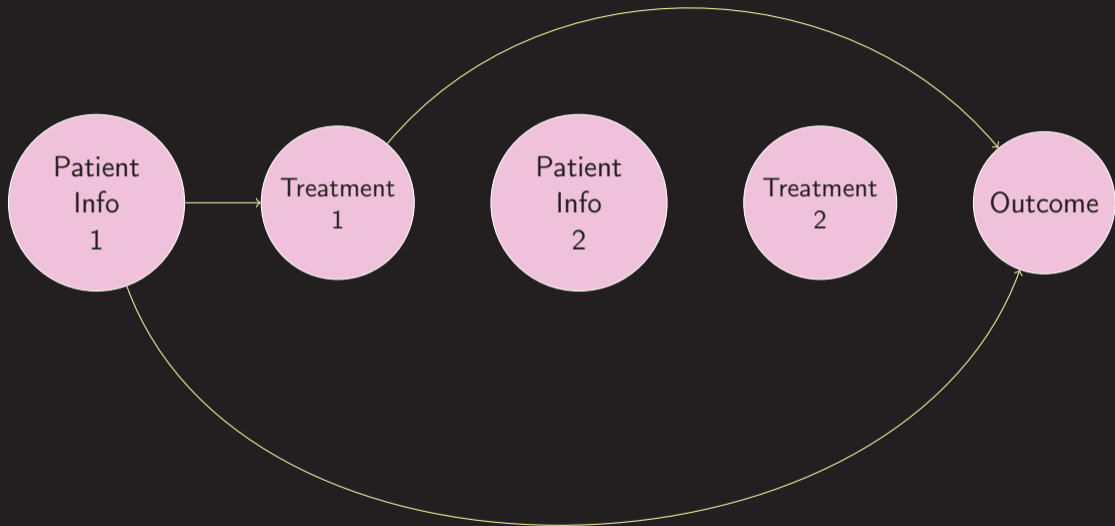
Dynamic Treatment Regimes

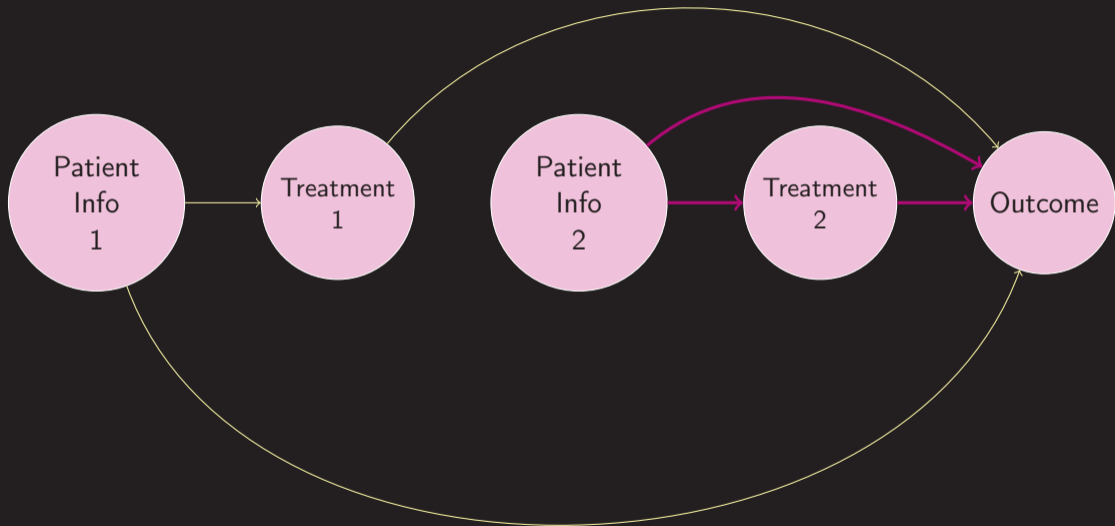


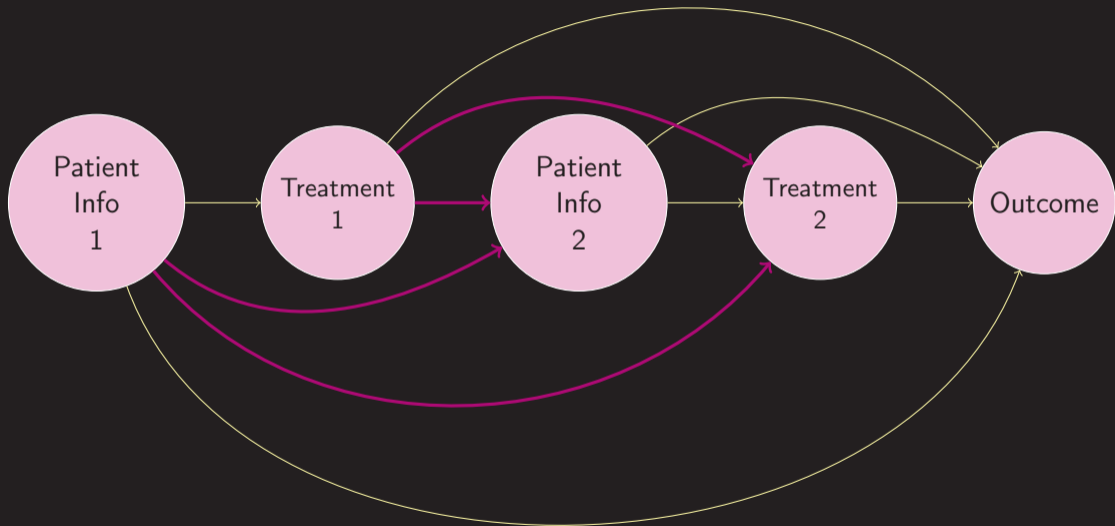
Dynamic Treatment Regimes











Patient
Info
1

A DTR refers to the set of
decision functions used to
assign treatment at each stage.

Outcome

The diagram features a central light gray rectangular box with a pink border containing text. To the left is a pink circle labeled 'Patient Info 1' and to the right is a pink circle labeled 'Outcome'. Two thin yellow curved lines connect the circles to the box, and a larger yellow curved line connects the two circles. Faint background text includes 'Treatment 1', 'Patient', and 'Treatment 2'.

A DTR refers to the set of
decision functions used to
assign treatment at each stage.

Outcome

Simplifying Assumptions

Binary Treatments

Referring to two competing treatment options at each stage.

Known Decision Points

Finite and deterministic number and timing of decisions.

At decision point j , we take $A_j \in \{0, 1\}$.

The work today does not require this assumption, though **discrete treatments** are required.

Simplifying Assumptions

Binary Treatments

Referring to two competing treatment options at each stage.

Known Decision Points

Finite and deterministic number and timing of decisions.

We require decisions to be made at a **finite** and **deterministic** number of points.

We assume that these are **discrete** and interchangeable between patients.

Notation Summary

1. Decision points:

$$j \in \{1, 2, \dots, K\}.$$

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4. Outcome (observed at time K):

$$Y \in \mathbb{R}.$$

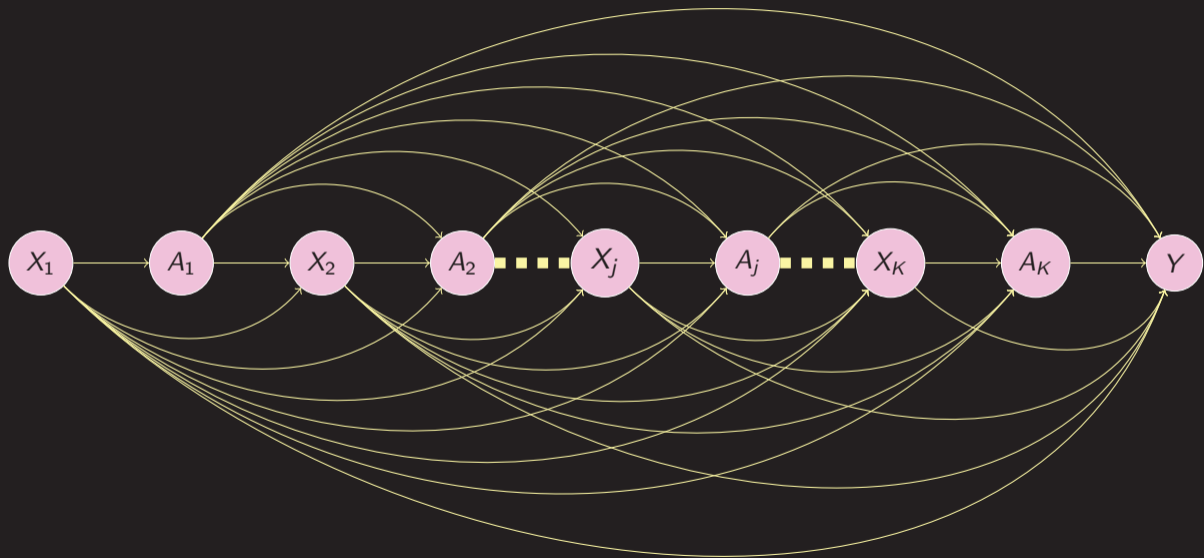
Optimal DTR Estimation

Our goal is to determine

$$d = \{d_1, d_2, \dots, d_K\}, \quad d_j: \mathbb{R}^{\ell_j^*} \longrightarrow \{0, 1\},$$

such that Y is maximized in expectation.

Why is DTR Estimation Hard?



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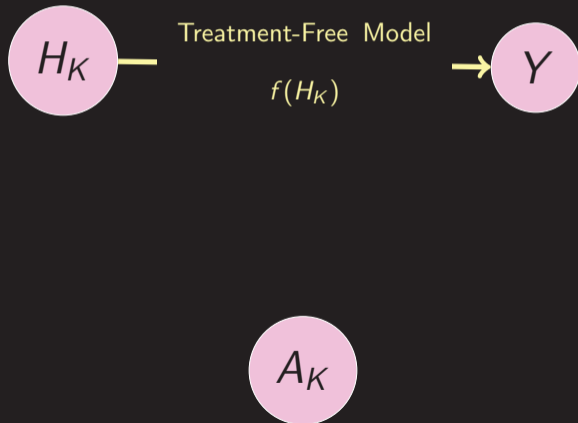


Modelling the Outcome

$$E[Y|A_K, H_K] = f(H_K) + A_K C(H_K)$$

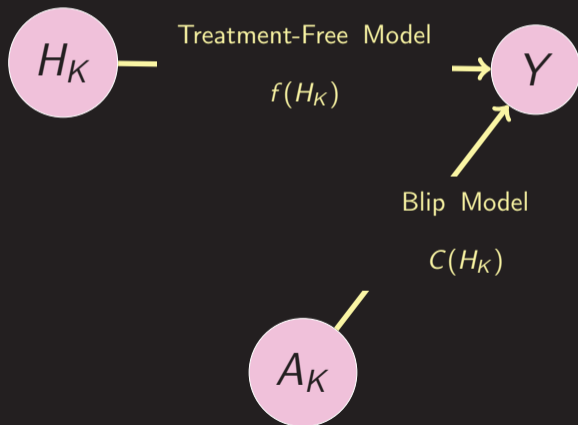
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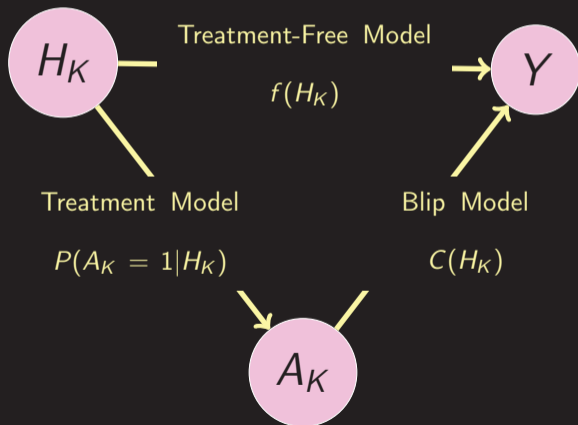
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1. Specify the required models at stage K .

$$C_K(H_K; \psi_K); \quad f_K(H_K; \beta_K); \quad \pi_K(H_K; \alpha_K).$$

G-Estimation: Mathematically (Robins 2004)

1. Specify the required models at stage K .
2. Solve for ψ_K in

$$\sum_{i=1}^n \lambda_K(H_{K,i}) \left\{ A_{K,i} - \underbrace{\pi_K(A_{K,i}; \alpha_K)}_{\text{Treatment Model}} \right\} \times \left\{ Y_i - A_{K,i} \underbrace{C_K(H_{K,i}; \psi_K)}_{\text{Blip Model}} - \underbrace{f_K(H_{K,i}; \beta_K)}_{\text{Treatment-Free Model}} \right\} = 0.$$

1. Specify the required models at stage K .
2. Solve for ψ_K in estimating equations.
3. Compute a **pseudo-outcome** for each individual.

$$\tilde{V}_j = \begin{cases} \tilde{V}_{j+1} + (A_j^{\text{opt}} - A_j)C_j(H_j; \psi_j) & j \leq K \\ Y & j = K + 1 \end{cases}.$$

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G-estimation produces **doubly robust** estimators for the **blip parameters**.

Causal Assumptions

SUTVA

Stable Unit Treatment Value Assumption

NUC

No Unmeasured Confounders.

Positivity

No Extrapolation Outside the Data.

There is only one **version** of each treatment option, and there is no **interference** between patients in the data.

Causal Assumptions

SUTVA

Stable Unit Treatment Value Assumption

NUC

No Unmeasured Confounders.

Positivity

No Extrapolation Outside the Data.

There are no factors which influence both the **treatment assignment** as well as the **outcome**, which are **not measured**.

Causal Assumptions

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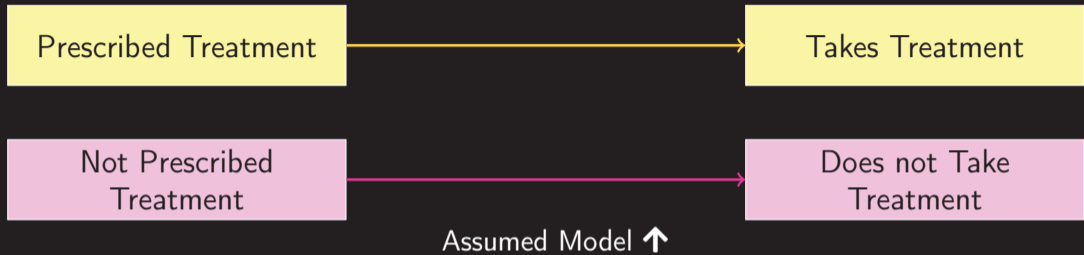
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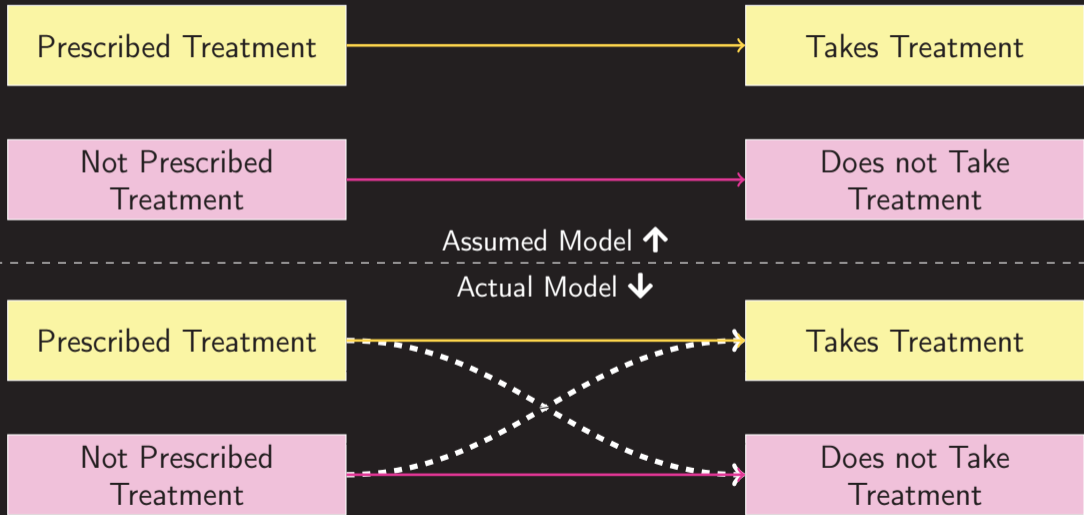
No Extrapolation Outside the Data.

All treatment regimes under consideration must have been **possible** for all individuals in the data.

The Problem of Nonadherence



The Problem of Nonadherence



Key Decision

Is the **intervention** or the **intended intervention** of more interest.

Intention-to-Treat Analyses

Treat the **assigned intervention** as the causal quantity of interest.

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Random Assignment

Treatment assignment is the randomized quantity, and so non-confounded.

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Real-World

Nonadherence exists in the “real-world”, and so should be factored-in.

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Treatment assignment is the randomized quantity, and so non-confounded.

Real-World

Nonadherence exists in the “real-world”, and so should be factored-in.

Standard Practice

It is standard practice, and better than as-treated or per-protocol.

ITTs can be very valuable ...
but this is not the whole story.

Problems with ITTs

Altered Causal Estimand

We estimate the effect of treatment assignment not treatment itself.

Non-Attenuation

Unpredictable as to whether an ITT correctly ranks multiple treatments.

Transportability Concerns

Are there differences in how patients adhere inside and outside the study?

There is likely substantial scientific interest in the **biological efficacy** of treatment, if it had been adhered to.

ITTs cannot estimate **treatment efficacy** in an unbiased manner.

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Are there differences in how patients adhere inside and outside the study?

Despite claims of **effect attenuation** under nonadherence, there is no statistical guarantee that **treatment rankings** are preserved.

ITTs cannot be used to compare treatments based on **treatment efficacy**.

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The adherence rates may differ between the sample and population.

ITT Effect = Adherence \times Treatment Efficacy.

Does adherence remain the same in the population?

Should we conduct research into
improving adherence?

Transportability Concerns

Should we use treatments in a supervised setting?

ITTs can be very valuable ...
but this is not the whole story.

See for instance Sheiner and Rubin (1995) or Shrier, Verhagen, and Stovitz (2017).

What other options do we really have?

ITTs for DTRs: A Justification

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4. Under certain assumptions, a “naive” OLS estimator for ψ has

$$\hat{\psi}(X, A^*) \xrightarrow{P} \psi^* = \psi [P(A = 1|A^* = 1) - P(A = 1|A^* = 0)].$$

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5. This quantity is such that $\text{sign}(X'\psi^*) = \text{sign}(X'\psi)$.

This is only true under the **exclusion restriction**, with **constant non-adherence probabilities**, in the **single-stage setting**.

Additional Problems with Nonadherence in DTRs

Stable Treatments

Do treatment options remain binary?

If a patient with $A^* = 1$ is non-adherent, is that the same as a patient $A = 0$?

Reported Treatments

What if we do not measure prescribed treatment?

When considering **nonadherence**, it becomes possible that **new treatment options** are introduced.

Additional Problems with Nonadherence in DTRs

Stable Treatments

Do treatment options remain binary?

Reported Treatments

What if we do not measure prescribed treatment?

We have focused on **prescribed** treatment as it compares to **actual** treatment. What about **reported** treatment?

$$A^* \longrightarrow A \longrightarrow A^\dagger.$$

Summary

To justify use of an ITT, we need to answer:

1. Is it the **right causal effect** or is the model **simple enough** to correspond with **treatment-efficacy**?
2. Does the **SUTVA** still hold, even when considering the **adherence data**?
3. Does the **NUC** assumption still hold, even when considering the **reported data**?

If not, we need **another alternative**.

Proposed Solution: A modified version of G-estimation

Treatment Prescription

Alter the treatment model to be a treatment-prescription model.

Additional Model

Add in a fourth component for adherence probabilities.

Alter Existing Models

Change the existing models to be computable, given observed data.

Instead of specifying a **treatment model**, giving the probability of receiving treatment, we specify a **treatment-prescription model**, giving the probability of treatment assignment.

Proposed Solution: A modified version of G-estimation

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In addition to the **blip**, **treatment-free**, and **treatment-prescription** models, we must now also specify a **misclassification** model.

Proposed Solution: A modified version of G-estimation

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Alter Existing Models

Change the existing models to be computable, given observed data.

When using **treatment indicators** in the existing models, we need to update the terms to be conditioned on **treatment assignment** instead. This involves making use of the **misclassification** model throughout.

The **blip parameters** are estimated by solving

$$\sum_{i=1}^n \lambda_K^*(H_{K,i}^*) \left\{ A_{K,i}^* - \underbrace{\pi_K^*(A_{K,i}^*; \alpha_K^*)}_{\text{Treatment Prescription Model}} \right\} \\ \times \left\{ Y_i - \underbrace{P(A_{K,i} = 1 | A_{K,i}^*, H_{K,i})}_{\text{Misclassification Model}} \underbrace{C_K^*(H_{K,i}^*; \psi_K^*)}_{\text{Blip Model}} - \underbrace{f_K^*(H_{K,i}^*; \beta_K^*)}_{\text{Treatment-Free Model}} \right\} = 0.$$

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 - ▶ Internal validation;
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Modified G-Estimation

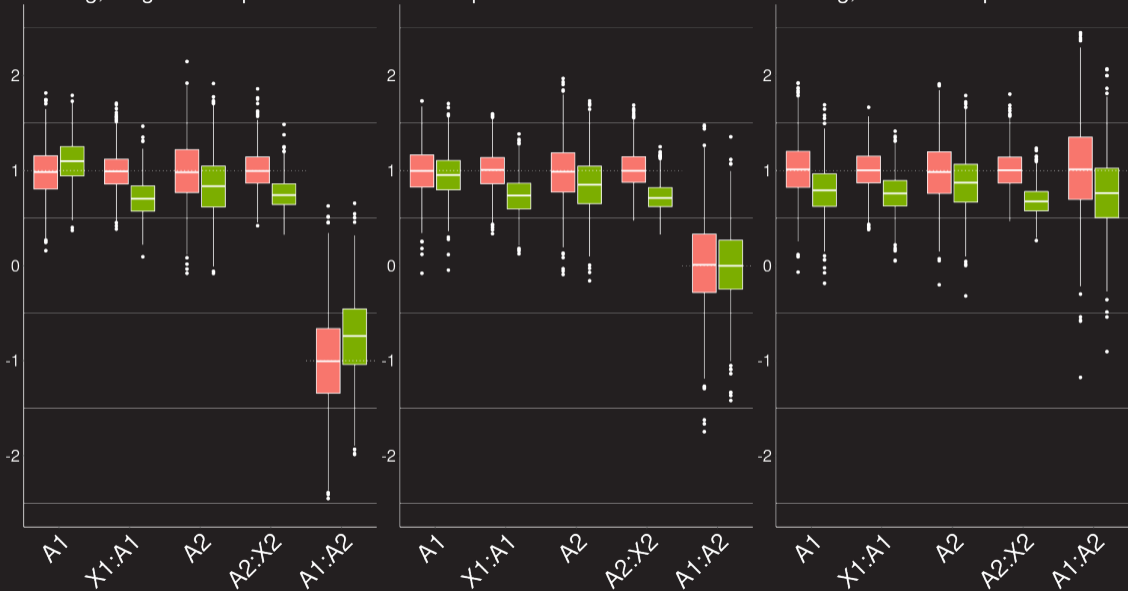
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4. Flexibility in the estimation of **misclassification models**. Can make use of:
 - ▶ Internal validation;
 - ▶ External validation;
 - ▶ Sensitivity analyses.
5. Provides estimates of both **treatment efficacy** and **adherence probabilities**, allowing ITT results to be recovered.

Strong, Negative Dependence

No Dependence

Strong, Positive Dependence

Parameter Estimates



Drawbacks to Modified G-Estimation

Despite the benefits to the modified G-estimation approach, there are further considerations to make.

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Extra Modelling

Both the blip and misclassification models need to be correct for valid estimation.

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Extra Modelling

Both the blip and misclassification models need to be correct for valid estimation.

Independence Assumptions

There are formal independence assumptions required for causal conclusions, which may be violated.


Conclusions

ITTs play an important role, but should be considered critically.


Approaches that estimate **treatment efficacy** directly are possible but may require further modelling, complicating the assumptions.


Thank You!

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Theorem 7.5.1 (Consistency of Modified G-Estimation)

Theorem

Suppose that for $j = 1, \dots, K$ and $i = 1, \dots, n$, we know $P(A_{i,j}^* | H_{i,j}^*)$ and $\pi_j^*(H_{i,j}^*, A_{i,j}^*)$, and we correctly specify the form of $C_j^*(H_{i,j}^*; \psi_j)$. Then the $\hat{\psi}_j$ which are estimated by solving $U_j^*(\hat{\psi}_j) = 0$ are consistent for the true ψ_j , under the following independence assumptions (I.A.):

- I.A. (1): $E[V_{j+1}(H_j) | H_j, A_j, \bar{A}_j^*] = E[V_{j+1}(H_j) | H_j, A_j]$ for all $j = 1, \dots, K$.
- I.A. (2): $E[C_j(H_j) | A_j = 1, H_j^*, A_j^*] = E[C_j(H_j) | H_j^*, A_j^*]$ for all $j = 1, \dots, K$.
- I.A. (3): $E[\nu_j(H_j) | H_j^*, A_j^*] = E[\nu_j(H_j) | H_j^*]$ for all $j = 1, \dots, K$.

Theorem 7.7.1 (Asymptotic Normality of Modified G-Estimation)

Theorem (Asymptotic Normality of Modified G-Estimation)

Suppose that for $j = 1, \dots, K$ and $i = 1, \dots, n$, we consistently estimate $P(A_{i,j}^* | H_{i,j}^*)$ and $\pi_j^*(H_{i,j}^*, A_{i,j}^*)$ through corresponding unbiased estimating equations, and we correctly specify the form of $C_j^*(H_{i,j}^*; \psi_j)$. Then the $(\hat{\psi}_1, \dots, \hat{\psi}_K)$ which are estimated as components when solving $U_j^* = 0$ (Equation (??)) are asymptotically normal, under the independence assumptions from Theorem 1, and the regularity conditions set out by Robins 2004 surrounding exceptional laws. Denoting $\hat{\Psi} = (\hat{\psi}_1, \dots, \hat{\psi}_K)$, we get that, as $n \rightarrow \infty$,

$$\sqrt{n} (\hat{\Psi} - \Psi) \xrightarrow{d} N(0, \Sigma_{\Psi}).$$

Here $\Sigma_{\Psi} = I_{\Psi} \Sigma_{\Theta} I_{\Psi}$, I_{Ψ} is the diagonal matrix with 1's on the diagonal entries corresponding to the locations of the Ψ parameters in Θ , Θ is the solution to $E[U^*(\Theta)] = 0$, and Σ_{Θ} is sandwich variance matrix based on U^* .

Pseudo Outcome Justification (Nonadherence)

In the event that there are no treatment indicators in the blip function, then the blip function is exactly known when ψ_j is known, and $A_{i,j}^{\text{opt}}$ will be correctly specified. Suppose that for C_{k+1} , only A_k is involved in the computation. Then, knowing the form of C_{k+1} we can say that

$$\begin{aligned} & E [A_{k+1}^{\text{opt}} C_{k+1}(H_{k+1}) | H_{k+1}^*, A_{k+1}^*] \\ &= P(A_k = 1 | H_{k+1}^*, A_{k+1}^*) E [A_{k+1}^{\text{opt}} C_{k+1}(H_{k+1}) | H_{k+1}^*, A_{k+1}^*, A_k = 1] \\ &\quad + (1 - P(A_k = 1 | H_{k+1}^*, A_{k+1}^*)) E [A_{k+1}^{\text{opt}} C_{k+1}(H_{k+1}) | H_{k+1}^*, A_{k+1}^*, A_k = 0] \\ &= \pi_k^*(H_{k+1}^*) I \{C_{k+1}(H_{k+1}^*, A_k = 1) > 0\} C_{k+1}(H_{k+1}^*, A_k = 1) \\ &\quad + [1 - \pi_k^*(H_{k+1}^*)] I \{C_{k+1}(H_{k+1}^*, A_k = 0) > 0\} C_{k+1}(H_{k+1}^*, A_k = 0). \end{aligned}$$

We can take

$$\begin{aligned} \tilde{V}_j &= \tilde{V}_{j+1} + \pi_{j-1}^*(H_j^*) I \{C_j(H_j^*, A_j = 1) > 0\} C_j(H_j^*, A_j = 1) \\ &\quad + [1 - \pi_{j-1}^*(H_j^*)] I \{C_j(H_j^*, A_j = 0) > 0\} C_j(H_j^*, A_j = 0) - \pi_j^*(H_{i,j}^*) C_j^*(H_{i,j}^*). \end{aligned}$$